An Initial Investigation into the Real-Time Conversion of Facial Surface EMG Signals to Audible Speech





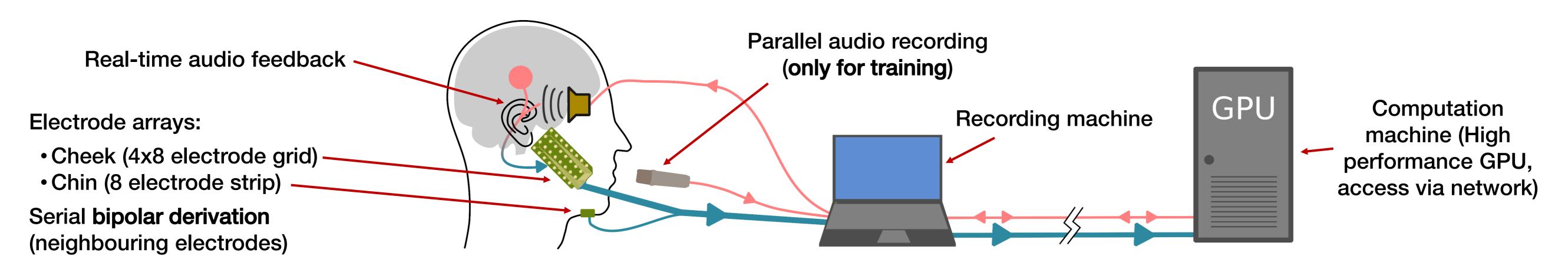
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Motivation

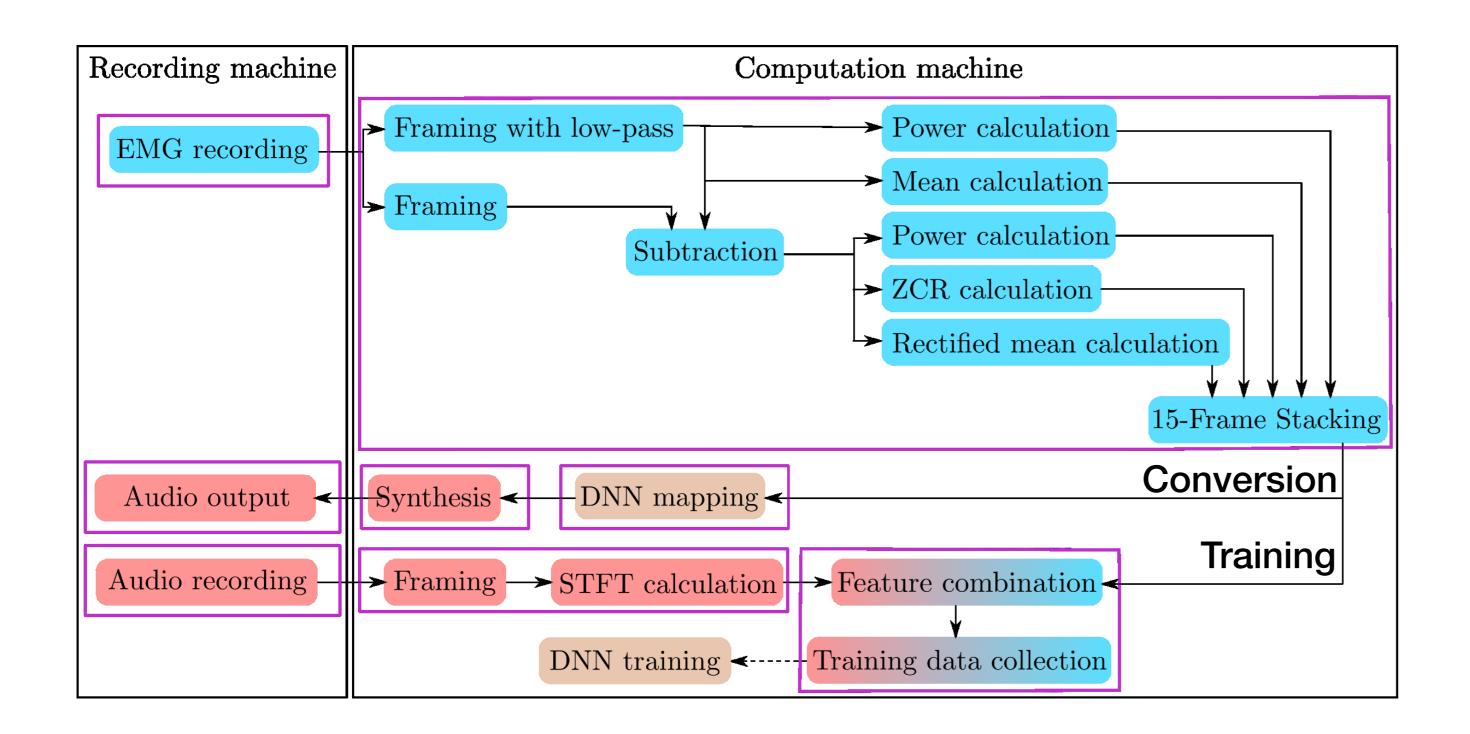
- Silent Speech Interfaces (SSIs): Speech interfaces that can be operated with no audible speech signal
 - → Applications in silent communication, loud environments, speech prostheses
- SSIs based on electromyography (EMG) work only with muscle movement
 - → Fully silent operation

- Previous EMG SSIs: Offline conversion, not real-time low latency capable
 - Real applications and research into feedback / coadaptation effects require this
 - → Need different system structure and algorithms

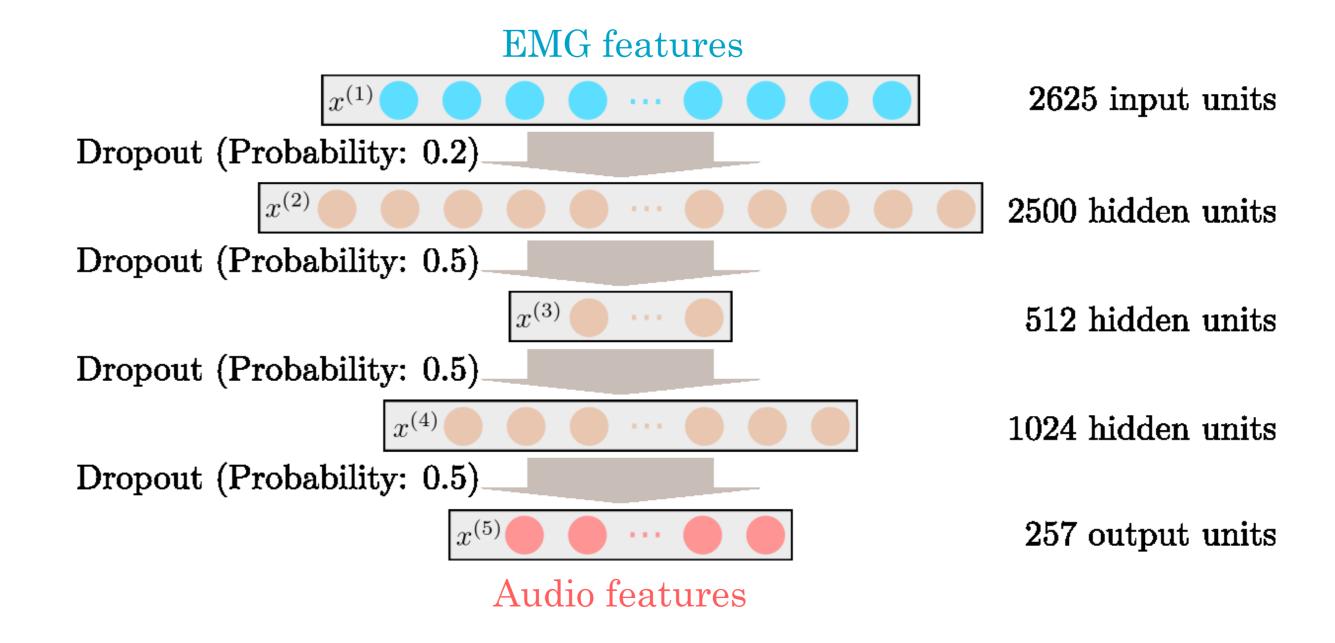


System Structure

• Broken down into modules that can run in their own processes to achieve real-time performance

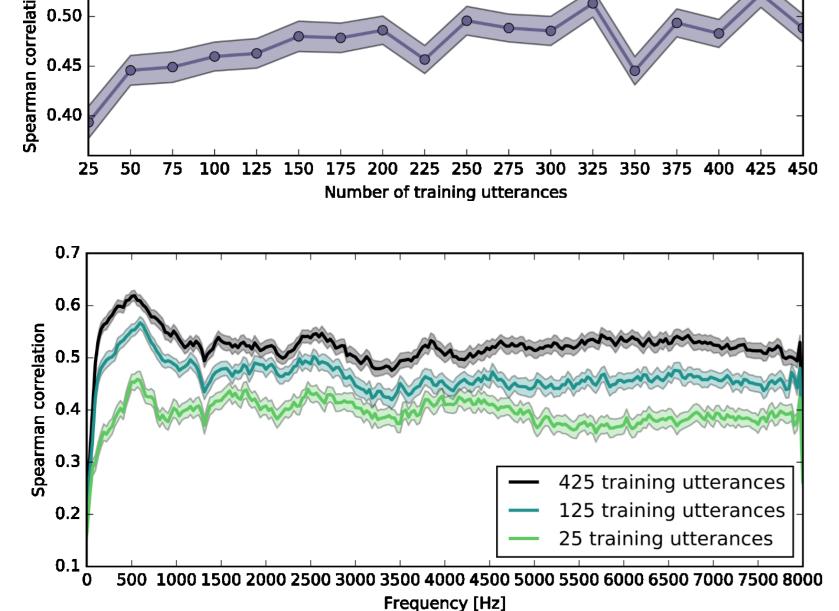


- Actual mapping: Uses deep neural networks
 - → Proven to work well in EMG-to-Speech conversion
 - → Training reasonably fast on modern GPU hardware
 - → ReL activation



Evaluation

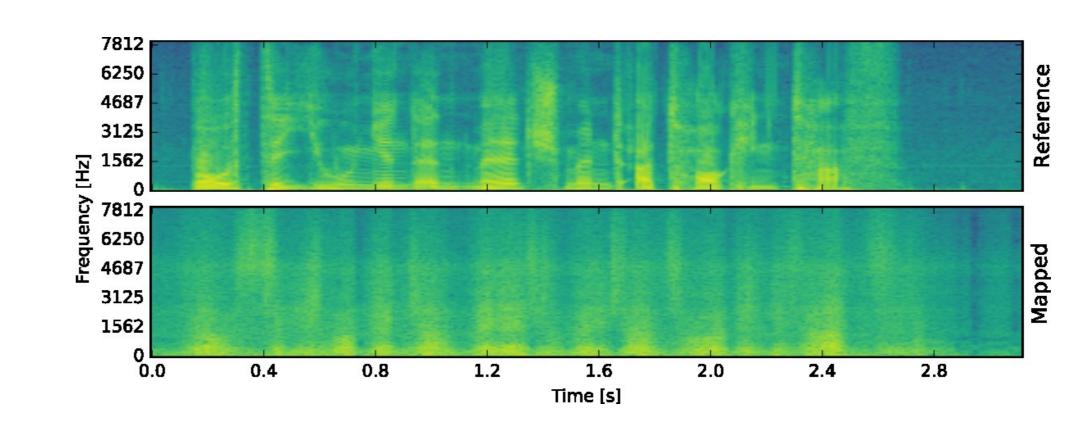
- Session-dependent systems: Less training data required means less recording / training time
 - → Evaluate training set size on pre-recorded data
 - → 125 to 150 utterances (~10 minutes) sufficient, diminishing returns afterwards



Nb. training utterances versus test set spectral correlation. Coloured area: standard error.

Spectrogram bandwise correlations on test set for three systems with different training set sizes. Coloured area: standard error.

- Latency: Four distinct categories of latency
 - → Network latency: Measured, sub-ms
 - → Buffer latency: Size of largest buffer, here: 40ms
 - → Computation latency: Measured, per 10ms frame:
 9.34ms (mean)
- In practice: higher latencies due to hardware latency (EMG amplifier, sound card)
- Next steps: Try to adapt existing systems to get closer to ideal quality, first feedback experiments



Spectrogram comparison: Reference (above) vs synthesized (with high-quality / ideal reference system trained using 450 utterances, below)

